

A Taste of (formal) Sound Reasoning

A Tutorial

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Linux Audio Conf 2015

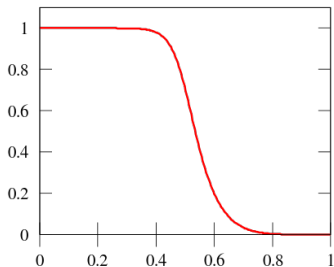
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<https://github.com/ejgallego/mini-faust-coq>

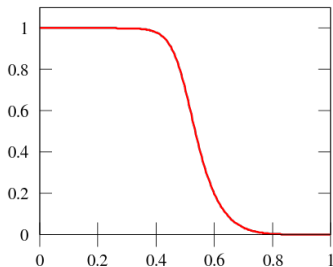
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What can we know about it?

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Natural questions are:

- ▶ Frequency response;
- ▶ Stability;
- ▶ Linearity/Time Invariance.

Answers given by standard DSP theory.

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Paradigm shift!

Certainty

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How do we know something is “absolutely” true?

Many possible answers

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In the Programming Languages field, we want computers to check knowledge for us!

How does it work?

Welcome to Evidence!

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We will build a particular kind of evidence for a property of our filter, then use the computer to validate it.

Types of Evidence

Bob Hi Alice, my dog is feeling weird!

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Logical Evidence: Proofs

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Proposition Examples

“Every even number is not prime.”

“Every complex polynomial has a root.”

“Every finite impulse filter is stable.”

Checking Validity: Inference

To check when a proposition holds, we need rules.

Rule Examples

“If A and B hold, B holds.”

“If P holds for 0 , and assuming P holds for n we can prove that P holds for $n+1$, then P holds for all n .”

The Theory of Forms

Truth

Truth lives in the idealistic, infinite universe.

$\Gamma \models \varphi$ if Γ is true, then φ is true

Proof

Reasoning lives in the concrete, syntactic universe.

$\Gamma \vdash \varphi$ φ can be proved from Γ

using a valid application of the rules.

Linking the Worlds

$\Gamma \models \varphi$ if Γ is true, then φ is true
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Main Properties

- ▶ Soundness: $\Gamma \vdash \varphi$ implies $\Gamma \models \varphi$.

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We are liberated from the complexity of the ideal, infinite world; we can now use mechanical, finitary rules to reason about it!

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A **crucial, fundamental** idea:

Programs are Proofs!
Types are Propositions!

Computational Evidence

Welcome to Coq!

```
aptitude install coq
```



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In Coq, proofs are precisely the well-typed functional programs. Type-checking validates our logical deductions!

BHK-Interpretation

Computational interpretation of logic

Type	Proof / Program
$P \wedge Q$	Record with proofs of P and Q .
$P \rightarrow Q$	Program that takes a proof of P , then produces a proof of Q .
$\forall(x : P), Q(x)$	Program that takes p , a proof of P , then produces a proof of $Q(p)$
$\exists(x : P), Q(x)$	Pair (p, q) of p , a proof of P , and q , a proof of $Q(p)$.
$P \vee Q$????

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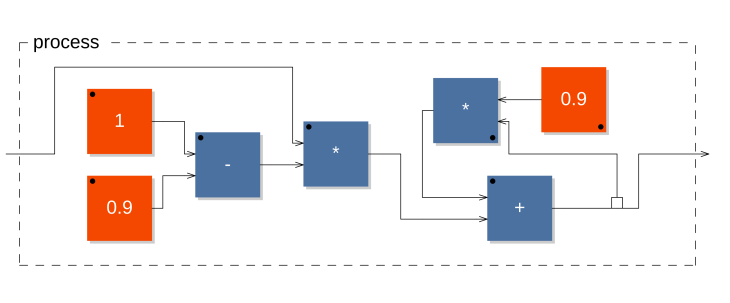
[Seriously, we'd love to hear about 4!]

Back to the Filter

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Using Faust:

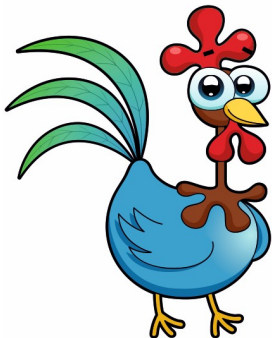
$$\text{smooth}(c) = *(1-c) : + \sim *(c)$$



[For $c = 0.9$]

Let's do it!

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Semantics

We can “write” Faust programs inside Coq. Now we want to run them.

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Output of Smooth

T:	1	2	3	4	5	6	7	8
I:	1.00	1.05	1.10	1.15	1.20	1.25	1.20	1.25
O:	0.10	0.19	0.28	0.37	0.45	0.53	0.61	0.68

What is Sound? Choices...

We need to choose how to represent sound in Coq? In the formal world, we *pay* for every detail.

- ▶ Conceptual representations? ($\mathbb{R} \rightarrow \mathbb{R}$).
- ▶ Infinite representations? ($\mathbb{N} \rightarrow \mathbb{R}$)
- ▶ Finite representation? ($\text{seq } \mathbb{R}$)

We'll use the last one.

Let's do it!

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When is Smooth Stable?

We are in good shape; now, when is smooth stable?

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Smooth is stable when $c \in (0, 1)$. Formally:

$$\forall i \in [a, b], c \in [0, 1] \rightarrow \text{smooth}(c) i \in [a, b]$$

Proving Stability

We can do the proof directly in Coq; it is not difficult but cumbersome in general.

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But we can use better, higher-level reasoning principles: Use *program logics* and target global properties over all samples.

Sampled Logic

Definition

A sample-level property φ holds for a signal s if it holds for all samples: $\forall n. \varphi(s[n])$.

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Definition

Assume a program f , then we write $\{\varphi\} f \{\psi\}$ for “for all inputs satisfying φ , the output of f satisfies ψ .”

Stability for smooth is written:

$$\{x \in [a, b]\} \text{ smooth } \{x \in [a, b]\}$$

Sampled Logic

$$\frac{\forall i_1, i_2, (\varphi_1(i_1) \wedge \varphi_1(i_2)) \implies \psi(i_1 + i_2)}{\{\varphi_1, \varphi_2\} + \{\psi\}} \textit{Prim}$$

$$\frac{\{\varphi\} \mathbf{f} \{\theta\} \quad \{\theta\} \mathbf{g} \{\psi\}}{\{\varphi\} \mathbf{f} : \mathbf{g} \{\psi\}} \textit{Comp}$$

$$\frac{\models \psi(x_0) \quad \{\theta, \varphi\} \mathbf{f} \{\psi\} \quad \{\psi\} \mathbf{g} \{\theta\}}{\{\varphi\} \mathbf{f} \sim \mathbf{g} \{\psi\}} \textit{Feed}$$

Stability Proof

$$\frac{\frac{\square}{\{I_{ab}\} * (1 - c) \{I_{abc}\}} \quad \frac{\frac{\square}{\{I_{abc}, I_{abc}\} + \{I_{ab}\}} \quad \frac{\square}{\{I_{ab}\} * (c) \{I_{abc}\}}}{\{I_{abc}\} + \sim * (c) \{I_{ab}\}}}{\{i \in [a, b]\} * (1 - c) : + \sim * (c) \{o \in [a, b]\}}$$

with:

$$I_{ab}(x) \equiv x \in [a, b]$$

$$I_{abc}(x) \equiv x \in [a * c, b * c]$$

$$I_{abc}(x) \equiv x \in [a * (1 - c), b * (1 - c)]$$

Stability Proof



Conclusions

- ▶ Interesting exercise; we learned a lot!
- ▶ The full language is basically done.
- ▶ We need your help! Let us know what would be interesting to check!
- ▶ Most complaints about plugins cannot be solved by verification.
- ▶ We are investigating a slightly different approach.
- ▶ Working on linear systems theory and frequency domain properties.

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